

Complementarity Problem Approach to Economic Power Dispatch of Nigeria Power System

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ABSTRACT

In this paper, a complementarity problem approach is used to solve the Economic Power Dispatch Problem of Nigeria Power System. Many approaches have been presented for solving Economic Power Discharge Problem; these approaches range from classical methods to more intelligen-based approaches. However, despite significant results of these methods, certain Imitations reduce their peformances and their suitability for online computation problems. In general, the optimization problem is formulated as Linear Complementarity Problem (LCP) when it is assumed that there is no transmission loss, and Nonlinear Complementarity Problem (NCP) if the transmission losses are included in the power balance equation. In this work, evolutionary programing, fast genetic algorithm, pattern search and hybrid self- adaptive differential evolution methods were also used to solve this problem. The simulation results indicate that the complementarity approach yields a cost value of ₩233.023 as compared to ₩233.624 and ₩233.956 given by evolutionary programming and fast genetic algorithm respectively for the Nigerian power system. The presented approach is more compact and offers superior speed of computation as compared to the evolutionary programming and fast genetic algorithm respectively.

INTRODUCTION

Economic Dispatch Problem (EDP) is an important issue in power system operation. The goal of the EDP is to minimize an objective function that reduces the power generation cost while satisfying various physical and operational constraints. The outcome of this approach is expected to improve output scheduling of online units. Under any load condition, EDP determines the power output of each plant (and each generation unit within the plant) which minimizes the overall generation cost (Wood and Wollenberg, 1996). In the traditional EDP, the fuel cost function of a generator is approximately

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represented by a quadratic function. Many efforts have been made to solve this problem (Ciornei and Kyriakides, 2013). Several optimization techniques, such as gradient method. lambda iteration and Newton's method have been used. In each of these methods, the result is affected by the incremental cost curves, which are piecewise linear and monotonically increasing, to find the global minimum. Furthermore, (Sharma and Mahor, 2013; Ndunagu et al., 2019a) proved that although conventional linear programming methods are simple and have high search speed, they have certain drawbacks and limitations. Some of these

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limitations are inherent in their performance and their holistic dependence on starting points.

During the last two decades, the EDP has been solved using several alternative methods such as Artificial Neural Networks (Abanihi and Ovabor, 2019), Evolutionary Programming (EP) (Surkha and Sumathi, 2011; Yuryerich and Wong, 1999: Somasundaram and Kuppusamy, 2006), genetic algorithms (GA) (Ndunagu et al., 2019b), Fast Genetic Algorithm (FGA) (Kumri and Sydulu, 2009), Particle Swarm Optimization (PSO) (Gang, 2003). As every algorithm is subject to free-lunch theory, there is need to explore the use of more algorithms or approaches on the EDP of the Nigerian Power System.

In this paper, a Complementarity Problem approach is presented to solve the economic Dispatch Problem (EDP) with guadratic cost functionn which is defined on the Nigeria Power System. The problem formulation is based on the minimization of the generation cost subject to demand and transmission losses constraints and constraints introduced by upper and lower bounds on generated power of each unit. Two cases are considered: (i) without transmission losses and ii) subject to transmission losses. In case (i), the

$$\min F_{1} = \sum_{i=1}^{n} F_{i}(P_{i})$$
$$= \sum_{i=1}^{n} a_{i}P_{i}^{2} + b_{i}P_{i} + c$$

problem formulation results finally in a Linear Complementarity Problem (LCP). In case (ii), the problem becomes nonlinear and it is formulated in a compact form as a Nonlinear Complementarity Problem (NCP).

The economic dispatch problem is a mathematical optimization problem. The goal of the solution is to achieve the optimal power dispatches from various power generating units for a determined time period to minimize the total generation cost while satisfying the specified constraint. The most commonly minimized function is the total cost of real power generation. The individual costs are assumed to be functions of active power generation and represented by quadratic equations. The constraints are the power balance equation and the upper and lower limits on the generated power by each unit.

A. Economic without Dispatch **Transmission Losses**

In this case the problem is to minimize the objective function subject to constraints of the demand load and minimum and maximum limits on the power output of the units. The mathematical optimization problem is as follows:

(1)

$$= \sum_{i=1}^{n} a_i P_i^2 + b_i P_i + c_i$$
Subject to:

$$\sum_{i=1}^{n} P_i = P_D$$
(2)

$$P_{i,\min} \leq P_i \leq P_{i,\max} \text{ for } i = 1, 2, ..., n$$
where:
i unit number
n number of units
F_i fuel cost function of the unit *i*
P_i power from ith generator
P_D demand load
P_{i,max} upper limit of the *i*th generator
P_{i,min} lower limit of the *i*th generator
Equation (3) can be written in the following form (Laan and Talman, 1989):

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$$\begin{split} P_i^1 &= P_i - P_{i,\min} \ge 0, \quad P_i^{11} = P_{i\max} - P_i \ge 0 \end{split} \tag{4} \\ \text{Adding these equations we obtain:} \\ P_i^1 + P_i^{11} &= P_{i,\max} - P_{i,\min} \end{aligned} \tag{5} \\ \text{And since } P_i^{11} \ge 0 \text{ this equation can be written in term of } P_i^1 \end{split}$$

$$P_i^{\rm l} \le P_{i,\max} - P_{i,\min} \tag{6}$$

The first equation in (4) can be written in terms of the new variable P_i^1 to obtain the power from the *i*th generator:

$$P_i = P_i^1 - P_{i,\min} \tag{7}$$

Substituting (7) in (1) and (2) the optimization problem can be expressed in terms of P_i^1 as follows:

minimize
$$F_i = \sum_{i=1}^{n} F_i (P_i^1 + P_{i,\min})$$
 (8)

Subject to the following constrains:

$$\sum_{i=1}^{n} P_{i}^{1} = P_{D} - \sum_{i=1}^{n} P_{i,\min}$$

$$P_{i}^{1} \ge 0$$
(9)
(10)

$$P_i^1 \ge 0$$

Constraint (9) can be written in the form of two inequality constants:

$$\sum_{i=1}^{n} P_{i}^{1} \le P_{D} - \sum_{i=1}^{n} P_{i,\min} - \sum_{i=1}^{n} P_{i}^{1} \le -P_{D} + \sum_{i=1}^{n} P_{i,\min}$$
(11)

The Problem described by the (8), (10), and (11) is an optimization problem, which contains both equality and inequality constrains, needs the deployment of the Karush-Kuhn-Tucker (KKT) optimality conditions (Han et al., 2011). Therefore these equations are rewritten in matrix form as follows:

$$\min F_{i} = (P^{1})^{i} DP^{i} + g^{i} P^{1} + k^{i}$$
Subject to:

$$eP^{1} \leq P_{D} - eP_{\min} - eP^{1} \leq -P_{D} + eP_{\min} IP^{1} \leq P_{\max} - P_{\min}, P^{1} \geq 0$$
(13)

Here
$$D = \begin{bmatrix} a_1 & 0 & \cdots & 0 \\ 0 & a_2 & \cdots & 0 \\ \vdots & \vdots & \cdots & \vdots \\ 0 & 0 & \cdots & a_n \end{bmatrix}, g = \begin{bmatrix} b_1 & + & 2a_1P_{1,\min} \\ b_2 & + & 2a_2P_{2,\min} \\ \vdots \\ b_n & + & 2a_nP_{n,\min}^1 \end{bmatrix}$$

And $k = \begin{bmatrix} c_1 + b_1P_{1,\min} + a_1P_{1,\min}^2 \\ c_2 + b_2P_{2,\min} + a_2P_{2,\min}^2 \\ \vdots \\ c_n + b_nP_{n,\min} + a_nP_{n,\min}^2 \end{bmatrix}$

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e is 1 x n is vector of ones, I is n x n identity matrix,

$$P^{1} = \left[P_{1}^{1}, P_{2}^{1} \dots P_{n}^{1}\right]^{i}, P_{\min} = \left[P_{1,\min}, P_{2,\min}, \dots, P_{n,\min}\right]^{i}$$

And $P_{\max} = \left[P_{1,\max}, P_{2,\max}, \dots, P_{n,\max}\right]^{i}$ (13)

The Karush-Kuhn-Tucker (KKT) Lagrange for the dispatch problem given by (12) and (13) is (Fletcher, 2000):

$$L = (P^{1})^{i} DP^{1} + g^{i} P^{1} + k^{i} + \lambda^{i} (eP^{1} - P_{D} + eP_{\min}) + \mu^{i} (-eP^{1} + P_{D} - eP_{\min}) + u^{i} (IP^{1} - P_{\max} + P_{\min}) + y^{i} (-P^{1})$$
(14)

Where λ , μ , u, and y are the Lagrange multipliers associated with the constraints. The Karush-Kuhn-Tucker (KKT) necessary optimality conditions for the above problem are:

$$\frac{\partial L}{\partial P^{1}} = 2DP^{1} + g + e^{i}\lambda - e^{i}\mu + Iu - y = 0, \\ \frac{\partial L}{\partial \lambda} = eP^{1} - P_{D} + eP_{\min} \le 0, \\ \frac{\partial L}{\partial \mu} = -eP^{1} + P_{D} - eP_{\min} \le 0,$$
(15)

Introducing the nonnegative slack variables $v^{\scriptscriptstyle +}, v^{\scriptscriptstyle -},$ and η the previous KKT conditions can be written as:

$$y - 2DP^{1} - e^{i}\lambda + e^{i}\mu - Iu = g, v^{+} + eP^{1} = P_{D} - eP_{\min}, v^{-} - eP^{1} = -P_{D} + eP_{\min},$$

$$\eta + IP^{1} = P_{\max} - P_{\min}$$
(16)

Comparing (16) with (5) we conclude that $\eta = P^{11} = [P_1^{11}, P_2^{11}, ..., P_n^{11}]$. Substituting in the above equation we obtain:

$$y - 2DP^{1} - e^{t}\lambda + e^{t}\mu - Iu = g, v^{+} + eP^{1} = P_{D} - eP_{\min}v^{-} - eP^{1} = -P_{D} + eP_{\min},$$

$$P^{11} + IP^{1} = P_{\max} - P_{\min}$$
(17)

where, the nonnegative variables fulfil the following complementarity conditions:

$$y \ge 0, P^{1} \ge 0, y^{t}P^{1} = 0 v^{+} \ge 0, \lambda \ge 0, v^{+t}\lambda = 0 v^{-} \ge 0, \mu \ge 0, v^{-}\mu = 0,$$

$$u \ge 0, P^{11} \ge 0, u^{t}P^{11} = 0,$$
 (18)

The system of (17) and (18) is a standard Linear Complementarity Problem (LCP) which can be written in the following form:

$$w - Mz = q$$
, $w \ge 0$, $z \ge 0$, $w^t z = 0$,

where

$$M = \begin{bmatrix} 2D & e^{t} & -e^{t} & I \\ -e & 0 & 0 & 0 \\ e & 0 & 0 & 0 \\ -I & 0 & 0 & 0 \end{bmatrix}, \ q = \begin{bmatrix} g \\ P_{D} - eP_{\min} \\ -P_{D} + eP_{\min} \\ P_{\min} - P_{\min} \end{bmatrix}, \ w = \begin{bmatrix} yv^{+}v^{-}P^{11} \end{bmatrix}^{t} \text{ and } z = \begin{bmatrix} P^{1}\lambda\mu u \end{bmatrix}^{t}$$
(19)

Economic Dispatch with Transmission Lines Losses

The EDP is considered here with the presence of transmission losses. Equation (2) is modified to account for such losses as follows:

$$\sum_{i=1}^{n} P_i = P_D + P_L$$
(20)

Where P_L is the total transmission loss and is given by the following equation [1]:

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$$P_L = \sum_{i=1}^{n} \sum_{j=1}^{n} P_i B_{ij} P_j + \sum_{i=1}^{n} B_{0i} P_i + B_{00}$$
(21)

Using (7) and (21) in (20) the power balance constraint reduces to:

$$eP^{1} - \left\{ (P^{1})^{t}B + 2P_{\min}^{t}B + B_{0} \right\} P^{1} - P_{D} - eP_{\min} + P_{\min}^{t}BP_{\min} + B_{0}P_{\min} + B_{00}$$
(22)
where B, B₀, and B₀₀ represent the B-coefficients of transmission loss formula.

Equation (22) can be written in a more compact form as follows:

$$\left\{ e - (P^1)^t B - V \right\} P^1 = 0$$

Here e is 1 x n is vector of ones, and V = 2N +B0 where $N=P_{\min}^{1}B$ and $Q = P_D - eP_{\min} + \{N + B_0\}P_{\min} + B_{00}$ Equality constraint given by (23) can be replaced by two inequality constraints (23)

$$\left\{e - (P^{1})^{t} B - V\right\}P^{1} \le Q - \left\{e - (P^{1})^{t} B - V\right\}P^{1} \le -Q$$

$$(24)$$
The Karush-Kuhn-Tucker (KKT) Lagrangian for the dispatch problem defined by the (5) (10)

The Karush-Kuhn-Tucker (KKT) Lagrangian for the dispatch problem defined by the (5), (10), (12), and (24) is: F / `` - -

$$L = (P^{1})^{t} DP^{1} + g^{t} P^{1} + k^{t} + \lambda^{t} \Big[\Big\{ e - (P^{1})^{t} B - V \Big\} P^{1} - Q \Big] - \mu^{t} \Big[\Big\{ e - (P^{1})^{t} B - V \Big\} P^{1} - Q \Big] + \mu^{t} (IP^{1} - P_{\max} + P_{\min}) + y^{t} (-P^{1})$$
(25)

where λ , μ , u, and y are the Lagrange multipliers associated with the constraints. The KKT necessary optimality conditions for the above problem are: $\gamma \tau$

$$\frac{\partial L}{\partial P^{1}} = 2DP^{1} + g + \left\{e - 2(P^{1})^{t}B - V\right\}^{t}\lambda - \left\{e - 2(P^{1})^{t}B - V\right\}^{t}\mu + u - y = 0,$$

$$\frac{\partial L}{\partial \lambda} = \left\{e - (P^{1})^{t}B - V\right\}P^{1} - Q \le 0, \qquad \frac{\partial L}{\partial \mu} = -\left\{e - (P^{1})^{t}B - V\right\}P^{1} + Q \le 0$$

$$\frac{\partial L}{\partial u} = IP^{1} - P_{\max} + P_{\min} \le 0$$
(26)

Introducing the nonnegative slack variables v⁺, v⁻, and η these KKT conditions can be written as:

$$y - 2DP^{1} - \left\{ e - 2(P^{1})^{t} B - V \right\}^{t} \lambda + \left\{ e - 2(P^{1})^{t} B - V \right\}^{t} \mu - u = g$$

$$v^{+} + \left\{ e - 2(P^{1})^{t} B - V \right\} P^{1} = Q$$

$$v^{-} - \left\{ e - 2(P^{1})^{t} B - V \right\} P^{1} = -Q \quad \eta + IP^{1} - P_{\max} + P_{\min}$$
(27)

Substituting η with P¹¹ we obtain:

$$y - 2DP^{1} - \left\{e - 2(P^{1})^{t} B - V\right\}^{t} \lambda + \left\{e - 2(P^{1})^{t} B - V\right\}^{t} \mu - u = g,$$

$$v^{+} + \left\{e - 2(P^{1})^{t} B - V\right\}P^{1} = Q$$

$$v^{-} - \left\{e - 2(P^{1})^{t} B - V\right\}P^{1} = -Q, P^{11} + IP^{1} = P_{\max} + P_{\min}$$
(28)

The nonnegative variables fulfil the following complementarity conditions:

$$y \ge 0, P^1 \ge 0, y^t P^1 = 0, v^+ \ge 0, \lambda \ge 0, (v^+)^t \lambda = 0, P^{11} \ge 0, u \ge 0, (P^{11})^t u = 0,$$

(29)

The system of (28) and orthogonality conditions (29) form a standard Nonlinear Complementarity Problem (NCP) which can be written as follows:

$$z \ge 0, \ M(z) \ge 0, \ z^{t} M(z) = 0, \ \text{where } z = \left[P^{1} \lambda \mu u\right]^{t}$$
 (30)

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NUMERICAL EXAMPLES

In this section, a six unit system with their cost function and power limits numerical examples are given to illustrate the developed method. The formulated LCP can be solved using iterative methods, Newton methods, and pivoting methods (Murty, 1983), here the LCP problem is solved using the MATLAB code pathlcp.m (written and maintained jointly by Michael C. Ferris and Madison and Todd Munson) (Ferris and Munson, 2000). On the other hand the formulated Nonlinear Complementarity Problem NCP can be solved using different algorithms $F_1(P_1) = 0.00156P_1^2 + 7.92P_1 + 561$ $F_2(P_2) = 0.00194P_2^2 + 7.85P_2 + 310$ $F_3(P_3) = 0.00482P_3^2 + 7.97P_3 + 78$ $F_4(P_4) = 0.00139P_4^2 + 7.06P_4 + 500$ $F_5(P_5) = 0.00184P_5^2 + 7.46P_5 + 295$ $F_6(P_6) = 0.00184P_6^2 + 7.46P_6 + 295$

Table I shows the results of the proposed method compared with fuzzy logic controlled genetic algorithm (FCGA) (Song *et al.*,1997) and genetic algorithm based on arithmetic crossover (GAAC) (Yalcoz *et al.*, 2001) when the load demand was 1800 MW. It's clearly evident from this table that the solution of the LCP

addressed in the literature, in this work the MATLAB LMMCP.M developed and written by Kanzow and Petra is used (Kanzow and Petra, 2004). Kanzow and Petra reformulated the NCP to nonlinear Least Square method and then they apply a Levenberg-Marquardt-type method to find the solution.

Examples without Transmission Lines Losses

First test system

The first system has six thermal units with the following cost functions and their associated constraints for each unit:

$$100 \le P_1 \le 600$$

$$100 \le P_2 \le 400$$

$$50 \le P_3 \le 200$$

$$140 \le P_4 \le 590$$

$$110 \le P_5 \le 400$$

$$110 \le P_6 \le 400$$

results in terms of operation costs is exactly the same as that obtained by the GAAC method, while the FCGA method produces higher operational costs. In general, strong correlation is evident between results obtained from all these methods.

Metho	Load	$P_1(MW)$	<i>P</i> ₂ (MW)	P ₃ (MW	$P_4(MW)$	P ₅ (MW	P ₆ (MW	<i>F</i> ₁ (\$/h)
d)))	
FCGA	180	250.49	215.43	109.92	572.84	325.66	325.66	16585.8
	0							5
GAAC	180	248.14	217.74	75.20	587.8	325.56	325.56	16579.3
	0							3
LCP	180	247.99	217.71	75.181	588.03	325.53	325.53	16579.3
	0	9	9		9			3

Second Test System

The second test system is the Nigeria power system, the 2015 version of the grid which essentially a 52-bus, 330-kV network interconnecting twenty-one thermal generating stations and three hydro stations to various load points. The quadratic cost functions for the various thermal units have been developed as the best curve fits using least square method to their actual operating cost data over a period of five years (2011 – 2015). Table II

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presents the cost coefficients so obtained for the twenty-one thermal units and their minimum and maximum loading limits. The network and its parameters suppressed herein can be found in (Abanihi, 2016). The power loss is computed from (20) with loss coefficients obtained via parameter estimation based on several power flow scenarios (Abanihi, 2016) for its largely radial network structure. The power system is solved for different values of demand load ranging between 2500 MW and 4000 MW. The individual generated power, minimum fuel cost, the total generated power, and the CPU time are shown in Table III.

S/N	Power Stations	P_{\min}	P _{max}	Cost Coefficients			
		(MW)	(MW)	a(\$/MW ² h)	b(\$/MWh)	c(\$/h)	
1	Egbin ST(gas)	118	1100	0.0000109	0.0284	3.92	
2	Sapele ST	33	223	0.0000591	0.0226	8.10	
3	Delta II-III	10	110	0.0000757	0.0326	6.47	
4	Delta IV	22	434	0.0000743	0.0334	9.85	
5	Geregu	14	450	0.0000201	0.0313	1.25	
6	Omotosho	29	480	0.0000514	0.0312	4.70	
7	Olorunsogo	10	293	0.0000294	0.0313	2.80	
8	Afarm IV-V	24	453	0.0000834	0.0289	2.03	
9	Sapele GT (NIPP)	30	373	0.0000105	0.0227	5.60	
10	Alaoji (NIPP)	34	87	0.0000200	0.0332	3.00	
11	Geregu (NIPP)	94	272	0.0000223	0.0314	1.00	
12	Olorunsogo (NIPP)	31	422	0.0000287	0.0313	1.70	
13	Omotosho (NIPP)	20	225	0.0000179	0.0313	2.64	
14	Ihovbe (NIPP)	91	120	0.0000200	0.0294	1.00	
15	Okapi	100	475	0.0000326	0.0286	4.53	
16	Afam VI	45	656	0.0000115	0.0286	8.00	
17	AES	51	242	0.0000133	0.0286	4.30	
18	Omoku	3	65	0.0000442	0.0314	1.30	
19	Ibom	10	101	0.0000189	0.0312	4.60	
20	Trans Amadi	4	31	0.0000315	0.0311	1.00	
21	Rivers IPP	20	160	0.0000215	0.0318	6.00	

Table II: Nigeria Generation Unit's Data

 Table III: Results Using LCP for Nigeria Power System

S/N	Power Stations	Loads on Power Stations				
		2500MW	3000MW	3500MW	4000MW	
1	Egbin ST(gas)	496.5275	122.8602	605.3239	288.83	
2	Sapele ST	34.9763	133.5573	185.8841	196.448	
3	Delta II-III	10.001	19.9982	98.9096	88.8314	
4	Delta IV	22.0039	61.0326	84.1693	107.2724	
5	Geregu	191.2735	189.9218	360.2352	442.2986	
6	Omotosho					
7	Olorunsogo	320.8359	686196	181.1366	179.6815	
8	Afarm IV-V	10.0625	29.9109	232.2028	278.7401	
9	Sapele GT (NIPP)	24	324.9404	156.3046	296.502	
10	Alaoji (NIPP)	101.8654	190.6673	140.6664	116.6221	

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S/N	Power Stations	Loads on Power Stations				
		2500MW	3000MW	3500MW	4000MW	
11	Geregu (NIPP)	94.0002	221.9574	136.9487	198.4023	
12	Olorunsogo (NIPP)	31.0156	233.4077	418.4326	365.4274	
13	Omotosho (NIPP)	183.6467	119.7283	194.2104	141.7964	
14	Ihovbe (NIPP)	92.1441	103.9853	93.2798	112.531	
15	Okapi	128.1011	272.8071	113.4729	233.0529	
16	Afam VI	480.9069	497.5713	74.8461	585.8328	
17	AES	193.03	192.9541	171.6475	119.293	
18	Omoku	3	49.1825	8.7339	23.1311	
19	Ibom	24.605	58.368	53.3774	63.081	
20	Trans Amadi	4	9.1717	8.6454	28.773	
21	Rivers IPP	20.0003	51.7764	137.1203	85.2807	
	Total Cost (\$/h)	170.8845	192.1326	210.8092	234.0267	
T	otal Power (MW)	2500	3000	3500	4000	
	CPU time (s)	18.92	20.56	19.53	21.34	

Examples with Transmission Losses

Here, the Nigeria power system considering losses is used as a third test case. The solution of the obtained NCP produces the amount of the generated power of each unit that results in the minimum generation cost. As mentioned previously the MATLAB program (LMMCP.M) written by Kanzow and Petra (Kanzow and Petra, 2004) is used to solve the problem. The obtained results for different load demand are shown in Table IV.

The results of the proposed formulation of the Nigeria power system

are compared with other methods such as Evolutionary Programming IDE (Surkha and Sumathi, 2011) and EP-OPF (Yuryerich and Wong, 1999), fast genetic algorithm approach (FGA) (Kumri and Sydulu, 2009), Pattern Search (PS) and a combination of Genetic Algorithm and Pattern Search (GA-PS) (Labbi and Attous, 2010), and Hybrid Self-adaptive Differential Evolution Methods SADE-ALM (Thitithasmrongchai and Eua-arpon, 2007). The load demand was 4000 MW and the obtained results are shown in Table V.

S/N	Power Stations	Loads on Power Stations				
		2500MW	3000MW	3500MW	4000MW	
1	Egbin ST(gas)	205.9341	308.5983	352.4037	512.4149	
2	Sapele ST	124.1365	45.3026	40.4529	198.8422	
3	Delta II-III	69.7759	40.1432	103.8878	59.9598	
4	Delta IV	40.302	173.8483	307.3493	133.892	
5	Geregu	333.5606	416.8211	28.3088	369.9527	
6	Omotosho	191.7182	148.1312	76.353	466.7263	
7	Olorunsogo	16.5794	34.4268	272.045	42.9636	
8	Afarm IV-V	97.5681	153.2491	240.1686	128.8502	
9	Sapele GT (NIPP)	33.7228	90.9435	346.7002	172.1573	
10	Alaoji (NIPP)	64.1003	54.2467	84.2063	85.0616	
11	Geregu (NIPP)	258.3033	193.955	169.4776	152.7668	
12	Olorunsogo (NIPP)	304.197	384.362	264.9911	365.7073	
13	Omotosho (NIPP)	112.1517	107.0225	171.7743	22.2689	

Table IV: Results	Using NCP for	Nigeria Power	System	Considering Losses
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S/N	Power Stations	Loads on Power Stations				
		2500MW	3000MW	3500MW	4000MW	
14	lhovbe (NIPP)	110.3343	108.4835	91.7641	115.1168	
15	Okapi	106.0276	161.626	122.4395	204.706	
16	Afam VI	82.9434	251.2419	419.4505	513.4202	
17	AES	103.1335	57.9065	240.9073	204.4638	
18	Omoku	49.1567	12.2706	11.4436	38.894	
19	Ibom	30.4134	78.3965	64.326	60.3256	
20	Trans Amadi	15.7154	20.057	16.91	18.2197	
21	Rivers IPP	149.9973	158.9679	74.6404	133.2903	
	Total Cost (\$/h)	171.9445	192.4928	211.9579	234.637	
Total Power Loss (MW)		24.18	26.78	38.23	56.34	
	CPU time (s)	22.5	24.63	23.6	25.62	

Table V: Results of IDE, EP-OPF, FGA, PS, GA-PS, SADE-ALM AND NCP for 6-Unit System

Method	<i>F</i> ⊤ (\$/h)	<i>P</i> ∟ (\$/h)	CPU Time
IDE	233.023	53.91	24.38
EP-OPF	233.624	54.28	24.71
FGA	233.956	54.97	24.93
PS	234.026	55.21	25.01
GA-PS	234.345	55.91	25.27
SADE-ALM	234.601	56.01	25.42
NCP	234.637	56.34	25.62

CONCLUSION

In this paper a new approach for the formulation of the economic power dispatch problem is presented. The problem without transmission losses taken into account in the power balance equation is formulated as Linear Complementarity Problem (LCP). Taking into account transmission losses the problem gets hard nonlinear, and formulated to present an efficient solution. Recently many efficient algorithms and software have been devised and developed. Real time example like the Nigeria power system shows that, in comparison with other methods, the presented approach provides an efficient, time saving, highly accurate, and cost effective technique with evident strong correlation with other well-known established techniques.

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